



*Designer | Developer*  
DESIGNER | DEVELOPER



# UX Design | Welding Pipe IOT

# Description:

---

- Welding Pipe IOT is a Mechanism for Internal Welding and External Welding in 6" pipe for oil industry.
- It includes internal welding, external welding, power control and hydraulic control with help of **Android app**, **Web-app** and **hardware remote**.

# Technology:

---

- HTML5, Android, Node.JS, MongoDB

**Welding Pipe IoT**

WELD CONFIG | REPLAY | SETTING | STATISTICS | FIRMWARE UPLOAD | CALIBRATION TOOL

IWM Module

Pass Name: NA    Zone Name: NA    Job No: 1    Joint No: W0002

OSCILLATION DATA	ROTATION DATA	LINEAR MOVE DATA
Center Position:	Current Position:	Current Position:
Width:	Rotation Speed:	Linear Speed:

**Welding Pipe IoT**

WELD CONFIG | REPLAY | SETTING | STATISTICS | FIRMWARE UPLOAD | CALIBRATION TOOL

IWM Module

Pass Name: NA    Zone Name: NA    Job No: 1    Joint No: W0002

OSCILLATION DATA	ROTATION DATA	LINEAR MOVE DATA
Center Position:	Current Position:	Current Position:
Width:	Rotation Speed:	Linear Speed:
Frequency:		

HORIZONTAL MOVE DATA	ANGULAR MOVE DATA	VERTICAL MOVE DATA
Horizontal Position:	Angular Position:	Vertical Position:
Horizontal Speed:	Angular Speed:	Vertical Speed:

# WeldConfig

---

- In this section user can performed operation related to internal, External welding machine with help of static remote and dynamic remote.
- It also provide facility to examine real time welding related data using laser camera, HD-view camera and different graph.

IWM Module

Pass Name:NA

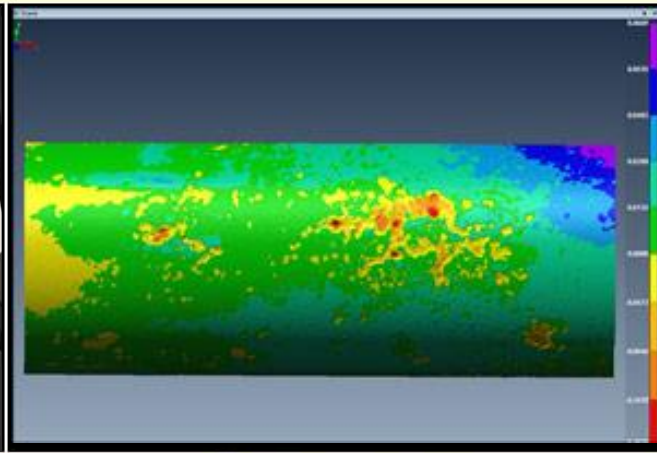
Zone Name:NA

Job No:1

Joint No:W0002



Welding Pipe IoT



**OSCILLATION DATA**

Center Position:

Width:

Frequency:

**ROTATION DATA**

Current Position:

Rotation Speed:

**LINEAR MOVE DATA**

Current Position:

Linear Speed:

**HORIZONTAL MOVE DATA**

Horizontal Position:

Horizontal Speed:

**ANGULAR MOVE DATA**

Angular Position:

Angular Speed:

**VERTICAL MOVE DATA**

Vertical Position:

Vertical Speed:

Control Panel Interface:

- Torch 1, Torch 2, Torch 3, Torch 4 (status indicators)
- Red circular refresh icon
- ANGLE (Left/Right), DWELL (Left/Right), WIDTH (Left/Right) - Control buttons with directional arrows
- Rotate (Left/Right) - Circular arrows
- HOME - Home icon
- Alt - Keyboard key icon
- REVERSE, Movement, FORWARD - Movement control buttons
- CONTI SCAN - Scan icon
- GAS, CONTACTOR, F. EXP, R. EXP - System function buttons
- CYCLE, ARC, STOP - Action buttons
- IWM, EWM, Dynamic - Mode selection buttons



IWM Module

Select widget:

**Oscillation Chart**

**Oscillation Data**

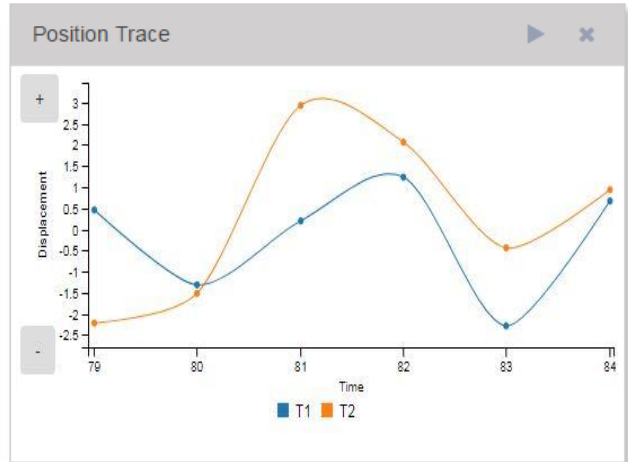
Horizontal Position:

Horizontal Speed:

**Rotation Data**

Current Position:

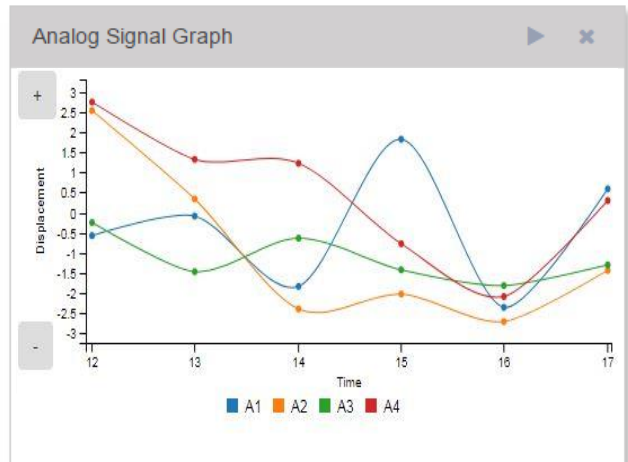
Rotation Speed:



**Analog Signal Chart**

Signal	Value
A1	
A2	
A3	
A4	

A1    A2    A3    A4



Digital Signal Chart

Digital Signal Graph

Torch 1   Torch 2   Torch 3   Torch 4

ANGLE   DWELL   WIDTH

Rotate

Alt   REVERSE   Movement   FORWARD   CONTI SCAN

GAS   CONTACTOR   F. EXP   R. EXP

CYCLE   ARC   STOP

EWM Module

Pass Name:

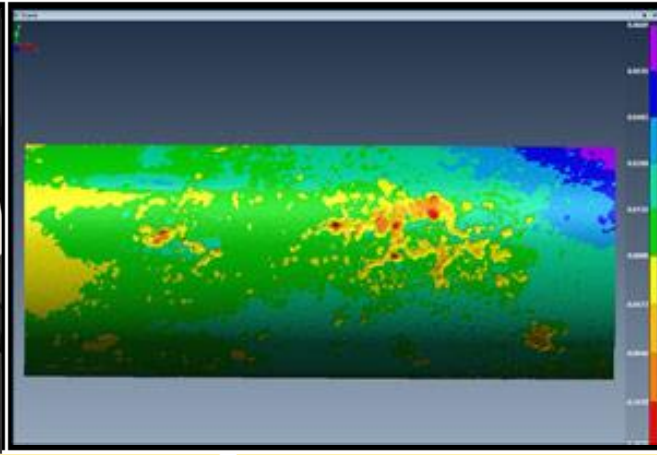
Zone Name:

Job No:

Joint No:



Welding Pipe IoT



OSCILLATION DATA

Center Position:

Width:

Frequency:

ROTATION DATA

Current Position:

Rotation Speed:

HORIZONTAL MOVE DATA

Horizontal Position:

Horizontal Speed:

ANGULAR MOVE DATA

Angular Position:

Angular Speed:

VERTICAL MOVE DATA

Vertical Position:

Vertical Speed:

Camera View

Data View

Torch 1 Torch 2 Torch 3 Torch 4

ANGLE DWELL WIDTH

Rotate

HOME CONTI SCAN

GAS CONTACTOR

CYCLE ARC STOP

IWM EWM Dynamic

IWM Module

EWM Module

Pass Name:NA

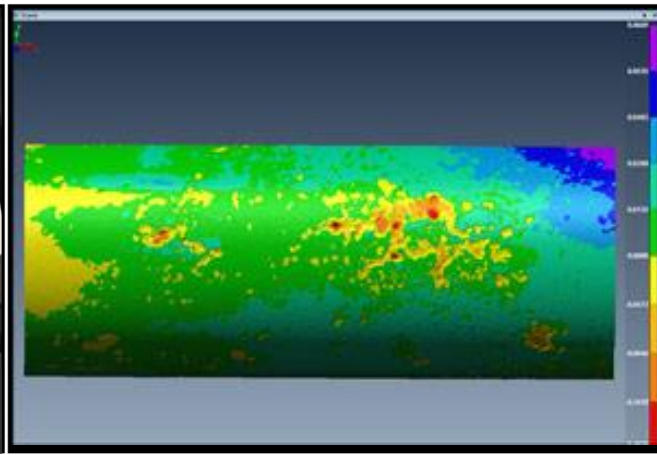
Zone Name:NA

Job No:1

Joint No:W0002



Welding Pipe IoT



OSCILLATION DATA

Center Position:

Width:

Frequency:

ROTATION DATA

Current Position:

Rotation Speed:

LINEAR MOVE DATA

Current Position:

Linear Speed:

HORIZONTAL MOVE DATA

Horizontal Position:

Horizontal Speed:

ANGULAR MOVE DATA

Angular Position:

Angular Speed:

VERTICAL MOVE DATA

Vertical Position:

Vertical Speed:

PLAY

NEXT PASS



Dynamic Control



IWM ASID

AS0001



EWM ASID

AS0001

Phase Difference

0

degree

Current Setting

IWM Weld Data

EWM Weld Data

Frequency:

Width:

Wire Feed Speed:

Travel Speed:

Ending Angle:

Target Voltage:

Target Current:

Weld Program No.:

Camera View

Data View

IWM

EWM

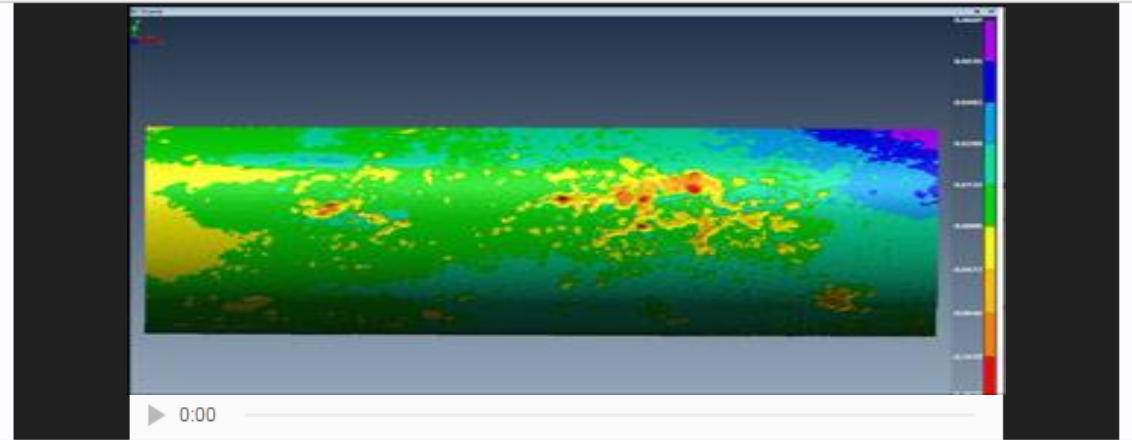
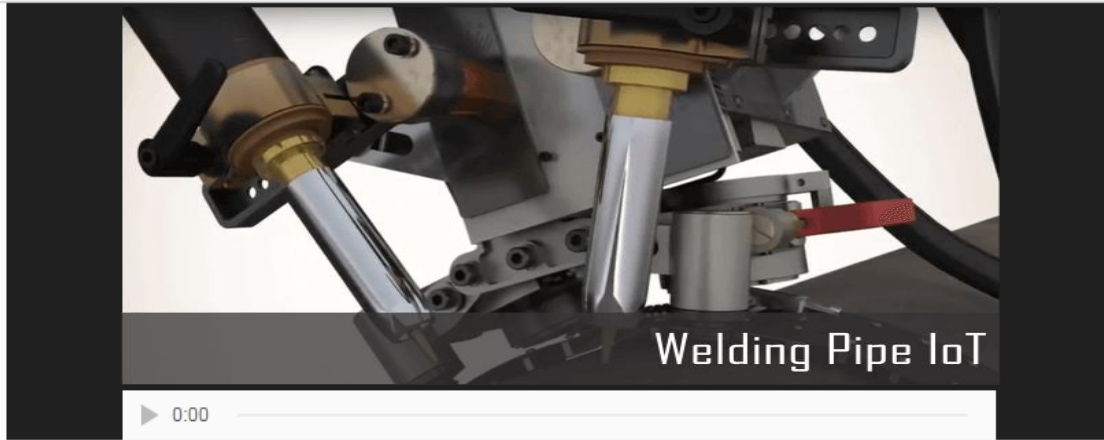
Dynamic

# Replay

---

- User can examine welding process , its recorded streaming , data in chart format using weld-id

ASID:  Run ID:  Video ID:



Analog data

Digital data

Oscillation

Analog Signal Chart

signal	Value
A1	
A2	
A3	
A4	

Analog Signal Graph



# Setting

---

- User can Store weld-operation , motor constant , dynamic preformation related value in mongo-DB using metric or imperial unit system.

Torch Rotation Movement

### Torch Module

#### Oscillation Config

##### Oscillation Config

Width	<input type="text" value="8"/>	mm
Width Increment	<input type="text" value="1"/>	mm
Frequency	<input type="text" value="1"/>	hz
Dwell Left	<input type="text" value="30"/>	ms
Dwell Right	<input type="text" value="30"/>	ms
Dwell Increment	<input type="text" value="10"/>	ms
Center Adjust Distance	<input type="text" value="1"/>	mm

##### Horizontal Move

Speed	<input type="text" value="20"/>	mm/s
Step Increment	<input type="text" value="2"/>	mm

Submit

Torch Angle

Measurement



Static Control



Dynamic Control



Motor Constant

Job Setup Weld Setup Help

Job Param Setup

Identification

Dynamic Seq. ID:		AS0001 ▾
Job ID:		J0001
Joint ID:		W0001

Motor Jog Setup

Horizonatal Jog Speed	mm	10
Vertical Jog Speed	mm	10
Angular Jog Speed	degree/s	10
Travel Jog Speed	mm	10

Update Delete

Static Control

Dynamic Control

Motor Constant

Job Setup Weld Setup Help

Weld Param Setup

Select Pass: P0001 Add

Pass P0001 out of 1

Total Zone:7

Current Pass : Pass P0001

Pass Information

Horizontal Jog Increment	mm	2
Vertical Jog Increment	mm	2
Angular Jog Increment	degree	4
OSCI Center Adjust	mm	1
Rotation Direction		anti-clockwise
Travel RampUp Time	sec	3
Travel RampDown Time	sec	3

ZONE Parameters

		Z0001	Z0002	Z0003	Z0004	Z0005	Z0006	Z0008
Ending Angle	degree	50	100	150	200	250	360	0
OSCI Width	mm	3	10	2.5	6	7	6	5
OSCI Frequency	hz	1	1.2	1.5	2	2	0.8	3.5
Dwell Left	ms	50	0	50	0	50	0	0
Dwell Right	ms	50	0	50	0	50	0	0
Travel speed	degree/s	3	4	5	6	7	8	10

Update



Static Control



Dynamic Control



Motor Constant

Torch

Rotation

Movement



### Torch Motor Constant

Oscillation

#### Oscillation Motor Constant

- |                       |                                   |        |
|-----------------------|-----------------------------------|--------|
| Step-Angle            | <input type="text" value="1.8"/>  | degree |
| Translation Factor    | <input type="text" value="6"/>    |        |
| Microsteps Resolution | <input type="text" value="64"/>   |        |
| Max Speed             | <input type="text" value="1150"/> | rpm    |
| Pulse Divisor         | <input type="text" value="0"/>    |        |
| Ramp Divisor          | <input type="text" value="0"/>    |        |
| Max Current           | <input type="text" value="128"/>  | Amp    |
| Ramp Percentage       | <input type="text" value="13"/>   | %      |
| Interpolation         | <input type="checkbox"/> Enable   |        |

Submit

Torch Angle

Vertical Move



Static  
Control



Dynamic  
Control



Motor  
Constant

# Statistics

---

- User can view real time statistics data of different module like torch , rotation, movement, central unit etc.



Torch



Rotation



Movement

CPU Usage



CPU Statistics

User

System

Idle

Memory Usage



Memory Statistics

Total Memory

Free Memory

Used

Cached

Network Statistics



Process Statistics



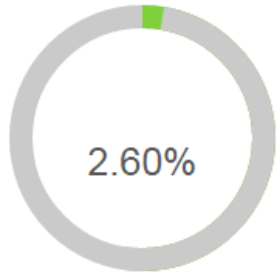
App Logs



Error Logs



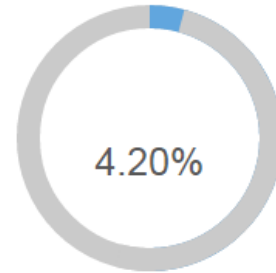
CPU Usage



CPU Statistics

User	1.9 %
System	0.7 %
Idle	97.2 %

Memory Usage



Memory Statistics

Total Memory	3826428 K
Free Memory	3665620
Used	160808
Cached	9704

Network Statistics

Network Statistics

Protocol	Received	Sent
IP	115020	162140
ICMP	12	5
ICMPMsg	12	5
TCP	114402	161900
UDP	127	150
IPExt	14833757	47380901

App Logs

Process Statistics

Process Statistics

PID	User	MEM%	CPU%	Process Name
3076	root	1.2	22.2	node
3970	root	0.0	11.1	top
1	root	0.0	0.0	init
2	root	0.0	0.0	kthreadd
3	root	0.0	0.0	ksoftirqd/0
5	root	0.0	0.0	kworker/u:0
6	root	0.0	0.0	migration/0

Error Logs

# firmware

---

- User can view current firmware version as well as update firmware of software in real time.

Sign In

admin

\*\*\*\*\*

[Forgot Password?](#)

Login



Hello , Admin [Log out](#)

### System Update

#### Module Information

Select Module :

Version	Application Firmware
Current Version	
Updated Version	

#### Upload To

Select Firmware :

#### Download To

Select Firmware :

# calibration

---

- User can examine each module expected result and actual result manually here .

Stop 00:00 Reset

Torch Angle

Speed: 0.1 degree/s

Distance: 0.1 degree

Result Window:

Exp. Time	Exp. Pos	Exp. RPM
0 ms	0 degree	0 rpm

Angle + Angle -

Horizontal Move

Speed: 0.1 mm/s

Distance: 0.1 mm

Result Window:

Exp. Time	Exp. Pos	Exp. RPM
0 ms	0 mm	0 rpm

Left Right

Vertical Move

Speed: 0.1 mm/s

Distance: 0.1 mm

Result Window:

Exp. Time	Exp. Pos	Exp. RPM
0 ms	0 mm	0 rpm

Up Down

Rotation

Speed: 0.1 degree/s

Distance: 1 degree

Result Window:

Exp. Time	Exp. Pos	Exp. RPM
0 ms	0 degree	0 rpm

Clock-wise Rotate Anti-Clock Rotate

Movement

Speed: 1 mm/s

Distance: 1 mm



*Designer | Developer*

Thank you !